



Search IEEE RAS

Search

0000

Resource Center

Robotics History

Join IEEE RAS

About RAS Membership

Conferences &

Publications

Technical Committees

Education, Outreach and Career

Awards & Recognition

Industry & Government

Home > About RAS > Latest News > ICRA 2016 Award Recipients Announced

V

>

Workshops

Commitment to Diversity > Governance > **Volunteer Resources** > **History of the Society** >

Latest News

E-News

Archival Newsletters Submit News

RAS Calendar

Contact RAS

ICRA 2016 Award Recipients Announced

Congratulations to the following ICRA 2016 Award Recipients! Winners were announced and honored during the RAS Awards Luncheon which took place on 19 May 2016 in Stockholm, Sweden.



Best Associate Editor Award Margarita Chli, ETH Zurich, Switzerland Jason Corso, University of Michigan, USA

Best Reviewer Award

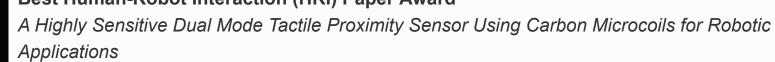
Jan Rosell, Universitat Politècnica de Catalunya, Spain Xiaolong Zhou, Zhejiang University of Technology, China Klaus Strobl, German Aerospace Center (DLR), Germany Giuseppe Loianno, University of Pennsylvania, USA

BEST PAPER AWARDS



ICRA Automation Best Paper Beyond Layers: A 3D-Aware Toolpath Algorithm for Fused Filament Fabrication Samuel Lensgraf, Ramgopal Mettu

Best Human-Robot Interaction (HRI) Paper Award



Hyo Seung Han, Junwoo Park, Tien Dat Nguyen, Uikyum Kim, Canh Toan Nguyen, Hoa Phung, Hyouk Ryeol Choi



ICRA Medical Robotics Best Paper Award

Image-Based Robotic System for Enhanced Minimally Invasive Intra-Articular Fracture

Giulio Dagnino, Ioannis Georgilas, Paul Köhler, Sanja Dogramadzi



ICRA Robot Manipulation Best Paper Award

Optimal Control with Learned Local Models: Application to Dexterous Manipulation Vikash Kumar, Emanuel Todorov, Sergey Levine



ICRA Robot Vision Best Paper Award Multi-Type Activity Recognition in Robot-Centric Scenarios

Ilaria Gori, J.K. Aggarwal, Larry Matthies, Michael S. Ryoo



ICRA Best Student Paper

Supersizing Self-supervision: Learning to Grasp from 50K Tries and 700 Robot Hours Lerrel Joseph Pinto, Abhinav Gupta



ICRA Best Conference Paper

A Convex Polynomial Force-Motion Model for Planar Sliding: Identification and Application Jiaji Zhou, Robert Paolini, James Bagnell, Matthew T. Mason

CHALLENGES

Airbus Shop Floor Challenge 1st Place - Team Naist, Japan 2nd Place - Team CriGroup, Singapore 3rd Place - Team Sirado, France

Humanitarian Robotics and Automation Technology Challenge Winner: Team Autobots: Qbotics Labs & Sastra Robotics, Kerala, India

Formal Methods for Robotics (FMR) Challenge

Winner: Team WPI, Worcester, MA, USA (Rohit Sheth, Nishan Srishankar, Joseph McMahon, Jie Fu) Winner: Team Caltech, Pasadena, CA, USA (Sumanth Dathathri, Richard Cheng, Richard M. Murray)

Mobile Microrobotics Challenge

1. Mobility Challenge

Winner: Team UTV Romania: Valahia University of Targoviste (Ioan-Alexandru Ivan, Florin Dragomir, Ioana Dulama Valentin Gurgu, Alin Bucurica, Nicolae Radulescu)

2. Assembly Challenge

Winner: University of Waterloo Nanorobotic Group: University of Waterloo (Tammy Liu, Manasa Kaniselvan, Ciara Azam, Natalie Pinchin)

3. Best in Show

Winner: Team UTV Romania: Valahia University of Targoviste (Ioan-Alexandru Ivan, Florin Dragomir, Ioana Dulama Valentin Gurgu, Alin Bucurica, Nicolae Radulescu)

Published: 10 June 2016

Easy Links



CASE 2024









Home | Sitemap | Contact IEEE RAS | Feedback | Accessibility | Nondiscrimination Policy | IEEE Ethics Reporting |

to advancing technology for the benefit of humanity.



RASonIEEE.